Title: Symbolic dynamics and renormalization of non-autonomous k periodic dynamical systems

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Abstract: The purpose of this paper was to introduce the symbolic formalism based on kneading theory, which allows us to study the renormalization of non-autonomous periodic dynamical systems.

Author Keywords: Non-autonomous difference equations; Skew-product dynamical systems; Symbolic dynamics; Renormalization; 39A05; 37B55; 37B10; 37E20

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